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ORIGINAL

The Effect of Frequency of Transcutaneous Electrical Nerve Stimulation (TENS) on Maximum Multi-finger Force Production

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Objective: The purpose of this study was to investigate the effect of transcutaneous electrical nerve stimulation (TENS) treatment on maximum voluntary force (MVF) production.

Methods: Ten healthy, young subjects (5 males and 5 females) participated in the study. MVF was recorded after a fifteen minute session of TENS stimulation under two conditions: low frequency (4 Hz) at maximum tolerable level and high frequency (110 Hz) at maximum tolerable level. TENS was provided simultaneously via self-adhesive electrodes placed on the finger pads of the index, middle, ring and little fingers. MVF was also recorded in a baseline condition with no TENS treatment. Data were collected in three different sessions on three consecutive days at the sametime of the day.

Results: Results from the study show that on an average, MVF increasesby 25% for the index, middle and little fingers for TENS treatment with 4 Hz frequency as compared to the baseline condition. However, the 110 Hz condition did not result in a significantly different MVF than the baseline condition during individual finger pressing tasks. In addition, while producing MVF with all the four finger stogether, MVF was 30% higher for the 4 Hz conditionin comparison to the baseline condition, and 15% higher for the 110 Hz condition in comparison to the baseline condition respectively.

Conclusion: The results suggest that stimulation ofafferent fibers onthe glabrous skinwith TENS could have a net facilitatory effect on the maximum motoroutput.

Keywords: Finger, Maximum finger force, Nerve simulation, Treatment

I. INTRODUCTION

Cutaneous feedback is one of the primary sensory modalities for successful completion of day-to-day dexterous manipulation tasks (Augurelle, Smith, Lejeune, & Thonnard, 2003; Johnson, 2001) and loss of cutaneous feedback from the fingers has been reported to produce lower magnitudes of maximum voluntary force (MVF) production (Augurelle et al., 2003; Shim et al., 2012). Lower MVF by the fingers is known to be a predictor of poor general health conditions (Sayer et al., 2006).

Although it is well established that loss of cutaneous feedback results in a decrease in maximal force production (Augurelle et al., 2003; Shim et al., 2012), if the maximum

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motor output could be enhanced by increasing the cutaneous feedback from the fingers is not yet known. In recent years, transcutaneous electrical nerve stimulation (TENS) has emerged as an important treatment to enhance the cutaneous sensation in patients with sensory deficits (Celnik, Hummel, Harris-Love, Wolk, & Cohen, 2007; Dickstein & Kafri, 2008). Although the exact neurophysiological mechanism of this phenomenon is not yet known, it has been suggested that TENS could enhance the somatosensory input by selectively stimulating certain afferent fibers, which in turn could modulate the motor output (Akyuz, Guven, Ozaras, & Kayhan, 1995; Urasaki, Wada, Yasukouchi, & Yokota, 1998). Further, different parameters of TENS are known to have a varied effect on the neuromuscular system, and frequency of TENS stimulation has been shown to be one of the most important parameters (Chesterton, Foster, Wright, Baxter, & Barlas, 2003; Walsh, Foster, Baxter, & Allen, 1995).

The purpose of this study is to investigate the effect of low frequency (4 Hz) TENS as well as relatively high frequency (110 Hz) TENS on MVF production during multi-digit pressing. It has been hypothesized that TENS treatment would facilitate the motor output by enhancing the cutaneous feedback during multi-digit pressing, thus resulting in greater MVF.

II. METHOD

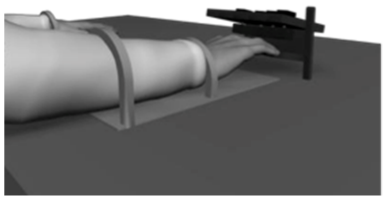
1. Subjects

Ten healthy young volunteers (5 males and 5 females, age: 21.0±2.3 years) participated in the study. These individuals were screened for any history of neurological disorders and were right handed according to the criteria of the Edinburgh handedness test. Participants were also administered a questionnaire to check their eligibility for TENS treatment and screen for any potential risks due to TENS. The experimental protocol was approved by the Institutional Review Board (IRB) of University of Maryland.

2. Experimental setup

Customized equipment consisting of four one-dimensional force sensors was used to measure the maximal finger forces (Models 208 M182 and 484B, Piezotronics Inc., Depew, NY, USA). C-shaped aluminum thimbles were fixed at the bottom of each sensor in order to rest the distal ends of the fingers while pressing. The sensors were attached to an aluminum frame with four slits, allowing for the adjustment of sensor position based on the subject's finger size. The subject's hand were bent slightly at the metacarpophalangeal joint (MCP), proximal interphalangeal joint (PIP) and distal interphalangeal joint (DIP) in order to make a dome shape, when the fingers rested on the testing equipment (Figure 1).

The frame was tilted 25 degrees with respect to the anterior-posterior axis and attached to a vertical aluminum panel. This panel had a slit allowing for two degrees of freedom: vertical translation and rotation around the z-axis. During the experiment subjects pressed down on the C-shaped thimbles. The forces produced by the fingers were



(a)

(b)

Figure 1. (a) Subjects were instructed to insert the distal phalanges of the fingers in the thimbles attached to a customized aluminum frame. (b) The wrists and the forearms of the subjects were rested in a wrist-forearm brace and held by Velcro straps.

transmitted to the sensors. The signals from the sensors were set at 1,000 Hz with a 16-bit A/D board (PCI6034E, National Instruments Corp., Austin, TX, USA) and were recorded by a software program created in LABVIEW (LabVIEW 7.1, National Instruments Corp., Austin, TX, USA). Force production data was transferred to a computer adjacent to the testing room. MatLAB (MatLAB7, MathWorks, Inc, Natick, MA, USA) programs were written for data processing and analysis.

3. Procedure

Five different finger combinations (four single-finger tasks and one four-finger task) for the MVF task were presented to the subjects. The subject performed the task once per each condition. The five conditions were presented to the subjects in a randomized order, with an interval of 3 min between consecutive pressing conditions. Once the subjects had comfortably positioned their fingers on their sensors, the investigators started the data collection program, which generated a "get ready" sound. This was followed by a "ding" sound after 2s. Subjects were instructed to "press as hard as possible with the task finger and relax the fingers once they feel they cannot press any harder". After 7s, another audio cue in the form of a "ding" sound was presented to indicate the end of the trial. No visual feedback was provided to the subjects.

This process was repeated for three different experimental conditions; 1) baseline, 2) 4 Hz. TENS treatment, and 3) 110 Hz TENS treatment. TENS was delivered via a portable unit (Elpha 3000 II, Danmeter A/S, biphasic, pulse width 200 μs) with circular, self-adhesive electrodes on the distal phalanges of index, middle, ring and little finger for fifteen minutes before pressing the sensors. During the MVF task with individual finger, TENS was provided to the corresponding finger and during the task with all fingers, TENS was delivered to all fingers. The intensity was self-selected by participants and set to the maximum tolerable level. Data were collected on three different days at the same time of the day. The order of treatment conditions was randomly assigned to the subjects.

4. Data processing

Maximum voluntary force (MVF) was measured as the peak forces produced by task finger or fingers during single-finger tasks and a four-finger task.

The force deficit for each finger was calculated by taking the difference of the maximum force produced by an individual finger in a single finger task and subtracting it from the force produced by the same finger in the four finger task.

$$\mathrm{FD}_i = F_{i,i} - F_{i,\mathrm{IMRL}} \tag{1}$$

Due to various factors, when a single finger is instructed to produce a force, the other fingers also produce and unintentional force. This phenomenon has been called finger independence. The average values of FI across all the four fingers were calculated as shown below (Equation 2).

$$\mathrm{FI} = 100 - \frac{{}_{j-1}^{n}[100\% * {}_{i=1}^{n}(F^{ij} / F_{m\ ax}^{i})/(n-1)]}{n} \tag{2}$$

Where $i \neq j$, n=4, $F_{\mathrm{m\ ax}}^{i}$ is the maximal force produced by the finger i and F^{ij} is the involuntary force produced by the non-task finger i during the i finger MVF task.

5. Statistics

One-way repeated measures ANOVAs were conducted to compare the MVF, FD and FI values between the three treatment conditions. The level of statistical significance was set at p=.05.

III. RESULTS

1. Maximum Voluntary Force (MVF)

The MVF values for the single finger tasks increased significantly compared to the baseline condition for the index, middle and little fingers after 4 Hz TENS treatment. Specifically, the MVF values increased 28% for the index

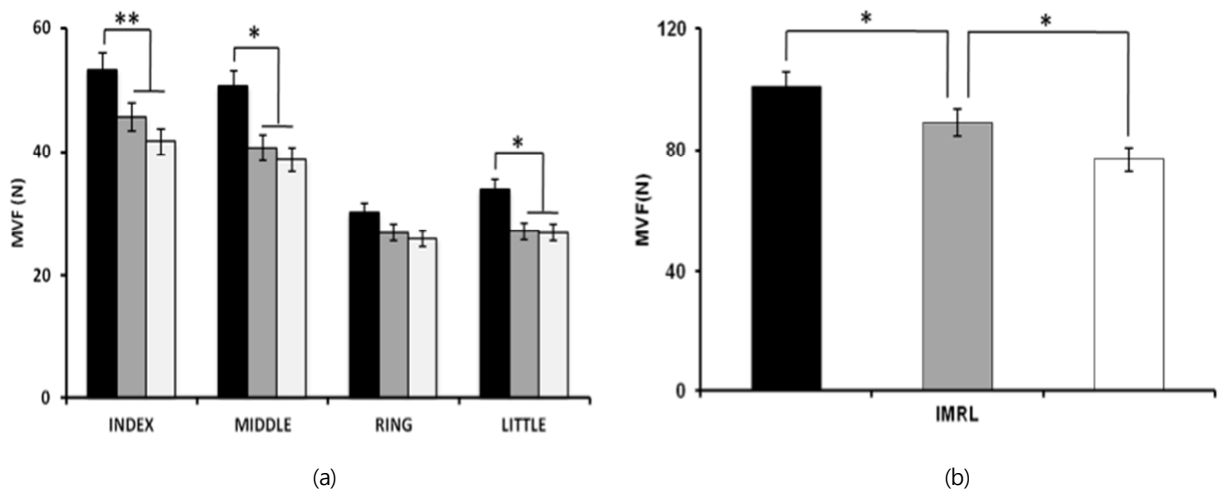


Figure 2. (a) MVF in N, produces by individual fingers of the participants. (b) MVF in N for all the four fingers pressing together. Means and standard errors are shown across the subjects. The 4 Hz TENS is represented in black, 110 Hz in grey and baseline condition in white. (*=$p<.05$; **=$p<.01$).

finger (from 41.6±6.3 N to 53.2±7.2 N), 30% for the middle finger(from 39.9±5.2 N to 49.2±6.3 N) and 25% for the little finger (from 24.6±4.2 N to 31.3±3.9 N) (Figure 2a). No significant differences were observed for the ring finger task. Further, MVF values for the 110 Hz condition were similar to the baseline condition during the individual finger tasks. These results were supported by ANOVA (Index: $F_{2,18}$ = 13.5; $p<.01$; Middle: $F_{2,18}$ = 5.83; $p<.05$; Little: $F_{2,18}$ = 6.05; $p<.05$). For the four finger pressing task, MVF values were 30% greater than the baseline for 4 Hz condition and 15% greater than the baseline for the 110 Hz condition. MVF increased from 77.0±9.2 N in the baseline condition to 89.0±11.6 N in the 110 Hz condition and 101.0±12.8 N in the 4 Hz condition (Figure 2b). The results were supported by ANOVA ($F_{2,18}$ = 8.94; $p<.01$).

2. Force Deficit (FD)

No significant differences in FD were found with TENS treatment.

3. Finger Independence (FI)

No significant differences in FI were found with TENS treatment.

IV. DISCUSSION

Maximum voluntary force (MVF) production by the digits is vital to perform everyday activities and its importance is well documented in the literature (Sayer et al., 2006; Slobounov, Johnston, Chiang, & Ray, 2002; Yue & Cole, 1992). Although TENS has typically been used as a modality of somatosensory stimulation to mitigate pain, the neurophysiological mechanisms of TENS are thought to excite the cortical motoneurons and affect motor output as well (Akyuz et al., 1995). While low intensity, high frequency somatosensory stimulation is known to significantly affect the motor output in humans, animal studies have suggested low frequencies could achieve similar results (Akyuz et al., 1995; Luft, Manto, & Ben Taib, 2005; Tinazzi et al., 2005; Walsh et al., 1995). Therefore, this study was undetaken to investigate the effect of TENS treatment with low and high frequencies on MVF during multi-digit pressing. Participants described that the 4 Hz condition gave them a "piercing" sensation, while the 110 Hz condition gave them a "tingling" sensation.

Consistent with our hypothesis, MVF increased significantly with TENS treatment in comparison to the baseline condition. Specifically, 4 Hz condition produced greater MVF as compared to the baseline condition and the 110

Hz condition for index, middle and little fingers. No significant differences were observed for MVF in the ring finger among the three experimental conditions, although the data exhibited a similar trend of higher MVF values of index, middle and little fingers with 4 Hz frequency. The ring finger is most difficult to control due to the fact that flexors and extensors are shared with other fingers and cortical neurons responded to movement of the ring fingers coupled with those of other fingers. Thus, it may lead to no changes in MVF in the ring finger. However, it needs to have further investigation for better understanding of TENS effect on the ring finger control.

However, no changes in MVF were observed in individual finger tasks after 110 Hz TENS treatment. In addition, 4 Hz condition produced greater MVF for all the four fingers pressing together, followed by 110 Hz and baseline condition respectively. 110 Hz TENS treatment also produced greater MVF values than the baseline conditions for all the four fingers pressing together.

The experimental setup for this study afforded to stimulate the finger pads and had a minimal effect on the intrinsic or extrinsic muscles of the hand directly. Thus, changes in motor output due to neuromuscular stimulation, as observed in some previous studies (Dickstein & Kafri, 2008), could therefore be ruled out in this study and the findings could be attributed to changes in somatosensory inputs alone. Previous studies providing visual or auditory feedback during maximum force production have shown a significant increase in force magnitude with the presence of appropriate sensory feedback (Kellis & Baltzopoulos, 1996; Sahaly, Vandewalle, Driss, & Monod, 2001). These studies suggest that under normal conditions, there is about 25~30% motor reserve which is not utilized typically and can be tapped into by using different methods like providing verbal motivation, visual or auditory feedback of force production.

Cutaneous feedback is known to be one of the major sensory modalities affecting the MVF production by the fingers of the hand (Collins, Knight, & Prochazka, 1999; Shim et al., 2012). Although the exact neurophysiological mechanism of changes in cutaneous sensation with TENS is not yet known, it has been shown that TENS treatment could temporarily increase the cutaneous sensitivity (Urasaki et al., 1998). TENS is thought to gate the somatosensory input at the peripheral level, through large afferent fibers and centrally through the cuneate nucleus (Luft et al., 2005; Nardone & Schieppati, 1989). There are four classes of low-threshold mechanoreceptors in human glabrous skin innervated by four classes of peripheral afferent nerve fibers. The neurons in the primary motor cortex have receptive fields in the periphery that receive inputs from the primary somatosensory cortex (Johansson, 1998). It is possible that low frequency TENS increased the cutaneous feedback, therefore changing the inputs to the primary somatosensory cortex, which in turn facilitate the inputs to the motor cortex, thus resulting in an increased motor output. These results are consistent with our recent study where MVF values decreased with the removal of cutaneous feedback (Shim et al., 2012).

Low frequency somatosensory stimulation of peripheral nerves has been known to increase the motor evoked potential as well as corticomotor excitability in previous studies (Mima et al., 2004; Nardone & Schieppati, 1989). Results from this study suggest that the increase in motor output could depend on TENS frequency as well as the digits involved in the task. Increase in MVF after short term TENS treatment (i.e., 30-minute TENS per a day) is consistent with results from such studies. The significant increase in MVF with short term TENS is encouraging and should be followed up with more elaborate studies to establish the most optimal combination of TENS parameters to obtain maximum motor output.

It is noteworthy that in most of the previous studies, high frequency TENS has been applied at sub threshold or threshold levels of detection (Mima et al., 2004). In contrast, this study used high intensity TENS for both the 4 Hz as well as the 110 Hz condition. High frequency TENS at sub-threshold intensity has been shown to produce significant improvements in hand motor performance (Mima et al., 2004). No changes in MVF for individual fingers observed in this study with 110 Hz frequency suggest that the neurophysiological mechanisms involved in motor facilitation could change depending on the combination of frequency and intensity of TENS and could be task dependent. It has been speculated that sub-threshold TENS enhances motor performance through the phenomenon called stochastic resonance (Manjarrez et al., 2002; Moss, Ward, & Sannita, 2004; Richardson, Imhoff, Grigg, & Collins,

1998). However, at higher intensities of TENS, like those employed in the current study suggest a mechanism of motor facilitation that is completely different from stochastic resonance.

V. CONCLUSION

In conclusion, this study provides an important technique to enhance the MVF production capacity by employing low frequency, high intensity TENS.

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